Application of Hierarchical Hybrid Encodings to Efficient Translation of CSPs to SAT

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Outline

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- The Log-Direct & Log-Order Encodings
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Motivation — SAT solving

- Boolean Satisfiability (SAT) solving has been an increasing impact on applications in various areas
- SAT solving = SAT solvers + SAT encodings
 - SAT solvers have reached a high level of development and efficiency.
 - > SAT encodings: ... limited and challenging
- Many applications in computer science can be expressed as Constraint Satisfaction Problems (CSPs), while hardly any such problems are originally given by SAT formulas
- → Translating CSPs into SAT!

Motivation – SAT encodings

- Direct encoding [deKleer89] (Support [Gent02]):
 - © Propagation: Forward checking (Arc consistency), e.g. NP-SPEC [Cadoli05], CSP2SAT 4J[Berre08]
 - 😕 # variables: BIG
- Order encoding [Tamura06]
 - Propagation: bound, e.g. Sugar [Tamura06], BEE [Metodi12]
 - 😕 # variables: BIG
- Log encoding [Walsh00]
 - 😊 # variable: small
 - Propagation: less powerful, due to long clauses
- Studying the log-direct & the log-order encodings!

Preliminaries – CSP

- A Constraint Satisfaction Problem (CSP) is a triple $\{0, 0, 0\}$, where:
 - $\succ v$ is a set of k multi-valued variables,
 - \triangleright \mathfrak{D} is the set of their domains,
 - \triangleright \mathcal{C} is a set of m constraints.
- A finite CSP: a finite set of variables, each having a finite domain
- The CSP problem is to determine whether there exists one assignment that satisfies all the constraints
- We consider a CSP variable v with the domain n values

Preliminaries – SAT

- A Boolean Satisfiability problem (SAT)
 - A conjunction normal form (CNF) is a conjunction of *clauses*, defined on a set of Boolean *variables*.
 - A clause is a disjunction of *literals*, where a literal is either a Boolean variable or its negation.
- A clause is
 - satisfied if at least one of its literals is assigned to true,
 - unsatisfied if all of its literals are assigned to false.
- The formula is satisfiable if there exists a truth assignment that satisfies all of its clauses, unsatisfiable otherwise
- The SAT problem is to determine whether a formula is satisfiable

Preliminaries – CSP2SAT

- The direct encoding [deKleer89] (support [Gent02])
 - ➤ Uses *n* propositional variables $d_{v_1}^{i_1} 1 \le i \le n$ to encode a CSP *v* with a finite domain $\{v_1, v_2, \dots, v_n\}$
 - Requires: at-least-one and at-most-one clauses
- The order encoding [Tamura06]
 - Uses a vector of n -1 propositional variables v_1, \dots, v_n^{n-1} to encode CSP v with a finite domain $\{v_1, v_2, \dots, v_n\}$
 - Requires: the domain constraint (a non-increasing vector)

$$\bigwedge_{i=1}^{n-2} \neg (\neg o_v^i \land o_v^{i+1}) = \bigwedge_{i=1}^{n-2} (o_v^i \lor \neg o_v^{i+1})$$

 \rightarrow The interval variables \rightarrow the propagation of bounds [5, 23, 32]

Preliminaries – CSP2SAT

- The log encoding [Walsh00]
 - \triangleright Uses $m = \lceil log_2 n \rceil$ Boolean variables.
 - Requires no at-least-one and at-most clauses, but prohibitedvalue clauses.
- Hierarchical Hybrid Encodings [Velev07]
 - A domain is recursively divided into smaller subdomains, until at the lowest level each subdomain contains a single a domain value. At each level of the hierarchy, one can choose a simple encoding and the number of subdomains on the next level.
 - ➤ The 12 simple encodings combined with a variety of structures led to a numerous way of translations of a domain to SAT → impractical

The Log-direct Encoding (1)

Basic Idea

The log-direct encoding is the first such hierarchical hybrid encoding, where the log encoding at level one has one indicator variable b_{ν} dividing the domain into two subdomains represented at level two with the direct encoding by mean of Boolean "direct" variables.

An assignment can be expressed

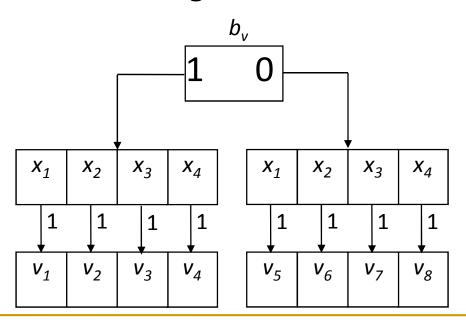
$$v = v_i \Leftrightarrow \begin{cases} b_v \wedge x_i & \text{if } 1 \le i \le \lfloor n/2 \rfloor \\ \neg b_v \wedge x_{i-\lfloor n/2 \rfloor} & \text{if } \lfloor n/2 \rfloor < i \le n \end{cases}$$

The Log-direct Encoding (2)

Proposition 1

The log-direct encoding to index the domain values of some CSP variable when encoding a CSP onto an equivalent SAT problem is sound and complete.

An illustration of encoding a CSP variable into SAT.



The Log-direct Encoding (3)

Proposition 2

The sparse encoding requires **n** Boolean variables to encode a CSP variable v with n domains whereas the log-direct encoding requires only **n/2+1** Boolean variables.

Proposition 3

Unit propagation applied to the log-direct encoding is incomparable to the direct encoding.

Suppose CSP variables: W, Y with domain {1, ..., 8}.

- And a CSP constraint W ≠3 ∨ Y≠5:
 - The log-direct : $(\neg b_W \lor \neg x_3) \lor (b_Y \lor \neg x_1^Y)$
 - The direct : $\neg d_W$ ³ $\lor \neg d_Y$ ⁵
 - \circ Now Y = 5...
- A CSP constraint W ≤ 5
 - The log-direct : b_Wvx₁
 - \rightarrow The direct: $d_W^1 \vee d_W^2 \vee d_W^3 \vee d_W^4 \vee d_W^5$
 - Now W ≠5...

The Log-direct Encoding (4)

Proposition 4

Unit propagation applied to the log-direct encoding is stronger than to the log encoding.

- 1. If unit propagation commits to particular truth assignments on the log encoding, then unit propagation commits to the same truth assignments on the log-direct encoding.
- If unit propagation generates the empty clause in the log encoding then unit propagation generates the empty clause in the log-direct encoding then (but the reverse does not necessarily hold).
- Proof: Similar to the proof of Theorem 15 [Walsh00]

The Log-order Encoding (1)

Basic Idea

The order-direct encoding is the first such hierarchical hybrid encoding, where the log encoding at level one has one indicator variable b_{ν} dividing the domain into two subdomains represented at level two with an order encoding by mean of Boolean order variables.

An assignment can be expressed

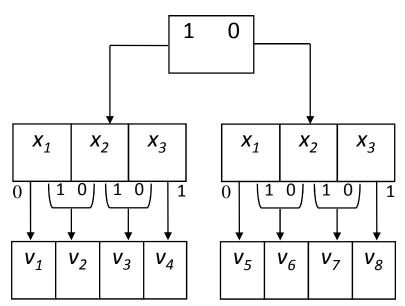
$$v = v_i \Leftrightarrow \begin{cases} b_v \wedge \neg x_1 & \text{if } i = 1 \\ b_v \wedge x_{i-1} \wedge \neg x_i & \text{if } 1 < i < \lfloor n/2 \rfloor \\ b_v \wedge x_{\lfloor n/2 \rfloor - 1} & \text{if } i = \lfloor n/2 \rfloor \\ \neg b_v \wedge \neg x_1 & \text{if } i = \lfloor n/2 \rfloor + 1 \\ \neg b_v \wedge x_{i-\lfloor n/2 \rfloor - 1} \wedge \neg x_{i-\lfloor n/2 \rfloor} & \text{if } \lfloor n/2 \rfloor + 1 < i < n \\ \neg b_v \wedge x_{\lceil n/2 \rceil - 1} & \text{if } i = n \end{cases}$$

The Log-order Encoding (2)

Proposition 5

The log-order encoding to index the domain values of some CSP variable when encoding a CSP onto an equivalent SAT problem is sound and complete.

An illustration of the log-order encoding to encode a CSP variable into SAT. b_{ν}



The Log-order Encoding (3)

Proposition 6

The sparse encoding requires **n-1** Boolean variables to encode a CSP variable v with n domains whereas the log-order encoding requires only **n/2** Boolean variables.

Proposition 7

Unit propagation applied to the log-order encoding is incomparable to the order encoding.

Proof: Similar to Proposition 3 by giving an appropriate example

Comparisons

Comparison of different encodings regarding to the number of variables and clauses required to encode a CSP variable with n value into SAT

Methods	# variables	# clauses
direct	n	$\sim n^2/2$
log-direct	~n/2	$\sim n^2/8$
order	n-1	~n
log-order	~n/2	~n/2

Experiments – Pigeon Hole Problems

Proving that *n* pigeons can not fit in *n-1* holes.

Instance	direct	l.direct	Speedup	order	l.order	Speedup
11	18.2	0.8	$22.8 \times$	3.3	0.9	3.7×
12	170.9	5.3	32.2×	15.2	4.2	$3.8 \times$
13	2,033.1	22.9	88.8×	72.0	15.5	4.6×
14	28,332.9	125.2	226.3×	1,013.4	65.8	15.4×
15	>86,400.0	661.2	>130.7×	7,394.6	232.2	31.8×
Min.	18.2	0.8	22.8×	3.3	0.9	3.7×
Max.	>86,400.0	661.2	226.3×	7,394.6	232.2	31.8×
Average	>7,638.8	163.1	>100.1×	1,699.7	63.7	11.9×

Experiments – Graph Coloring Problems

- Requiring an assignment of colors to the vertices of an undirected graph, such that no two adjacent vertices share the same color.
- The instances taken from [Color03]

Instance	K	direct	l.direct	Speedup	order	l.order	Speedup
DSJC125.9	9	35.6	0.6	57.5×	0.7	0.5	1.4×
	10	274.8	1.6	$171.8 \times$	2.3	1.3	$1.8 \times$
	11	10,839.2	7.0	$1548.5 \times$	8.1	3.8	$2.1 \times$
DSJC250.9	9	71.9	5.4	$13.1 \times$	3.6	3. 4	$1.1 \times$
	10	376.8	9.2	$41.0 \times$	7.4	4.5	1.6×
	11	11,150.8	213.8	52.2×	42.2	142.0	$0.3 \times$
miles750	9	15.6	0.3	$58.0 \times$	0.6	0.2	$2.8 \times$
	10	187.5	0.7	$267.9 \times$	1.9	0.6	$3.2 \times$
	11	3,214.1	4.5	$714.2 \times$	15.5	3.1	$5.0 \times$
miles1000	9	18.8	0.3	$49.6 \times$	0.4	0.3	$1.1 \times$
	10	319.0	0.9	$354.4 \times$	3.0	0.9	$3.3 \times$
	11	8,932.9	5.1	1751.5	21.0	3.9	$5.4 \times$
miles1500	9	26.8	0.6	$44.8 \times$	0.9	0.5	$1.7 \times$
	10	463.4	1.3	$356.5 \times$	2.5	0.9	$2.8 \times$
	11	11,295.2	6.8	$1661.1 \times$	20.7	3.6	$5.8 \times$
queen12_12	9	6.8	0.3	$21.5 \times$	0.5	0.2	$2.5 \times$
	10	28.6	0.7	$38.7 \times$	1.7	0.7	$2.2 \times$
	11	152.3	4.7	$32.3 \times$	5.2	3.9	$1.3 \times$
queen13_13	9	8.4	0.3	$23.4 \times$	0.7	0.3	$2.4 \times$
	10	63.7	0.8	$75.0 \times$	1.9	0.9	$2.1 \times$
	11	473.7	4.7	99.7×	8.3	3.5	$2.4 \times$
queen14_14	9	11.75	0.4	$28.7 \times$	0.7	0.3	$1.9 \times$
	10	141.4	0.9	$157.1 \times$	2.2	0.9	$2.4 \times$
	11	967.3	4.8	$201.0 \times$	15.3	0.9	$17.0 \times$
queen15_15	9	19.6	0.4	$49.0 \times$	0.9	0.4	$2.3 \times$
	10	214.9	1.1	$195.4 \times$	3.2	1.0	$3.2 \times$
	11	1237.3	5.3	$230.0 \times$	15.3	4.0	$3.8 \times$
queen16_16	9	16.2	0.6	$26.6 \times$	0.6	0.5	$1.2 \times$
	10	128.9	1.2	$107.4 \times$	3.7	1.1	$3.4 \times$
	11	2,194.9	5.1	$430.4 \times$	60.4	5.1	$11.8 \times$
school1	9	44.6	1.6	$27.6 \times$	1.3	1.2	$1.1 \times$
	10	345.7	4.5	$76.8 \times$	5.2	2.0	$2.6 \times$
	11	3,858.0	10.2	$378.2 \times$	9.8	7.6	$1.3 \times$
2-FullIns 5	5	0.3	1.7	$0.2 \times$	2.0	0.2	$\times 8.8$
	6	42.5	3,762.6	$0.01 \times$	4,842.5	16.0	$301.5 \times$
5-FullIns	7	0.7	6.9	$0.1 \times$	2.0	0.4	$5.1 \times$
	8	109.65	3,966.7	0.01×	4,235.8	12.4	341.6×
Min.		0.3	0.3	-0.01×	0.4	0.2	0.30×
Max.		11,295.2	3,966.7	1,751.5×	4,842.5	142.0	341.6×
Average		1,555.7	217.4	252.5×	252.7	6.3	$20.6 \times$

Experiments — Open Shop Problems

- Finding the minimize the makespan such that given n jobs and m workstations, each job has to be processed on a workstation at least once
- The instances taken from [Taillard]

Instance	M	S/U	direct	l.direct	Speedup	order	l.order	Speedup
41	192	U	19.4	1.3	14.9×	0.09	0.15	0.6×
	193	S	20.1	1.3	15.5×	0.17	0.23	$0.7 \times$
42	235	U	35.7	1.9	$18.8 \times$	0.11	0.22	$0.5 \times$
	236	S	37.3	1.7	21.9×	0.14	0.20	$0.7 \times$
4 ₃	270	U	65.9	2.7	$24.4 \times$	0.25	0.31	$\times 8.0$
	271	S	70.1	2.6	$27.0 \times$	0.16	0.24	$0.7 \times$
4_4	249	U	42.8	2.3	18.6×	0.17	0.29	$0.6 \times$
	250	S	44.1	1.7	$25.9 \times$	0.16	0.25	$0.6 \times$
4 ₅	294	U	77.1	3.3	$23.4 \times$	0.19	0.35	$0.5 \times$
	295	S	78.5	2.7	29.1×	0.12	0.20	$0.6 \times$
5 ₁	299	U	127.5	6.2	$20.6 \times$	0.71	0.65	1.1×
	300	S	126.7	7.1	$17.8 \times$	0.72	0.69	$1.0 \times$
52	261	U	130.9	8.8	14.9×	0.84	0.99	$\times 8.0$
	262	S	129.5	7.7	16.8×	0.75	0.59	$1.3 \times$
5 ₃	327	S	190.1	16.9	11.2×	0.57	1.1	$0.5 \times$
	328	S	198.4	14.7	13.5×	2.0	1.8	$1.1 \times$
54	309	U	257.8	17.4	$14.8 \times$	2.3	2.6	$0.9 \times$
	310	S	176.6	13.5	13.1×	1.2	1.7	$0.7 \times$
5 ₅	325	U	408.6	20.8	19.6×	4.4	4.1	$1.1 \times$
	326	S	174.2	19.0	$9.2 \times$	1.3	2.7	$0.5 \times$
7 ₁	436	S	252.2	130.0	1.9×	7.1	8.1	$0.9 \times$
	437	S	296.4	161.0	$1.8 \times$	11.7	9.0	1.1×
7_2	444	S	213.4	168.9	$1.3 \times$	12.8	12.1	1.1×
	445	S	265.6	144.2	$1.8 \times$	5.1	10.7	$0.5 \times$
7 ₃	470	S	669.1	349.3	1.9×	53.8	28.7	$1.9 \times$
	471	S	750.6	482.9	1.6×	51.0	40.8	$1.3 \times$
7_4	463	S	637.1	271.5	$2.3 \times$	19.8	12.4	1.6×
	464	S	275.5	160.7	$1.7 \times$	10.6	5.7	1.9×
7 ₅	416	S	268.3	142.0	1.9×	27.3	15.1	$1.8 \times$
	417	S	320.4	99.7	3.2×	11.9	4.9	2.4×
Min.			 1 9:4	1.3	1.3×-	0.07	0.15	0.5×
Max.			750.6	482.9	$29.1 \times$	53.8	40.8	$2.4 \times$
Average			186.9	75.5	13.0 X	6.1	5.1	1.0 X

Experiments – All Interval Serial Problems

Arranging a permutation of the *n* integers ranging from differences between adjacent numbers are also a permutation, of the numbers from *1* to *n-1* [csplib].

Finding all solutions

Instance	direct	l.direct	Speedup	order	l.order	Speedup	Sol
13	252.0	26.2	9.6×	6.0	18.3	0.3×	3200
14	1,787.5	162.5	11.0×	16.0	58.2	$0.3 \times$	9912
15	13,660.0	206.0	66.3×	52.7	265.8	$0.2 \times$	25592
16	>86,400.0	742.4	>116.4×	107.4	702.5	$0.2 \times$	55920
Min.	252.0	26.2	9.6×	6.0	18.3	0.2×	
Max.	>86,400.0	742.4	>116.4×	107.4	702.5	$0.3 \times$	
Average	>25,524.9	284.3	>50.8 X	45.5	261.2	0.3 X	

Conclusions

- Although we used only clasp solver, but similar results were obtained for other solvers (lingeling, riss3G).
- The log-direct encoding (mentioned by [Velev07] but not tested) significantly outperforms the direct encoding, with runtime speedups of one to two order of magnitude (increasing with the size of the instances).
- The log-order encoding, a hierarchical hybrid encoding based on a new combination of simple encodings. In general, the log-order encoding is comparable with the order encoding.
- Two simple encoding with the powerful propagation

Future Works

- Further study the use of the log-direct and log-order encodings for a wide variety of real-life problems
- Features of these problems that might be more efficiently explored by the different encodings, namely with large domains, where more than one indicator variable at the first level of encoding might be more suitable
- We will also develop a SAT-based CSP solver, like Sugar [Tamura09] with advanced improvements [Metodi12]

Thank you for your attention!

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